

Non-singular Transformation:-

A linear transformation  $T$  is said to be non-singular if  $N(T) = \{ \underline{0} \}$ . [  $\underline{0}$  is also known as the trivial solution ]

Note: If a transformation  $T$  is non-singular, then nullity = 0.

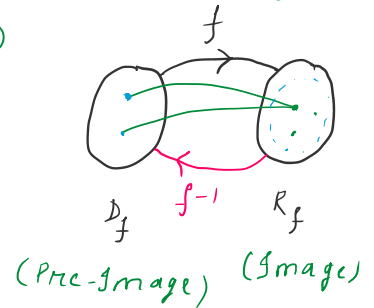
Singular Transformation:-

A transformation  $T$  is singular if  $\exists$  a vector  $\underline{x} \neq \underline{0}$  s.t  $T(\underline{x}) = \underline{0}$ .

Discussion: Fn  $f(x) : f: D_f \rightarrow R_f$ .

**Injective fn:** If  $f(x_1) = f(x_2) \Leftrightarrow x_1 = x_2 ; x_1, x_2 \in D_f$ .

**Surjective fn:** Consider  $y \in R_f$ . Then  $f(x)$  (onto fn) will be surjective if  $\exists$  atleast one  $x \in D_f$  s.t  $f(x) = y$



**Bijjective fn:** Injective + surjective.  
(one-one-correspondence).

**Inverse of a Fn:**  $f^{-1} : R_f \rightarrow D_f$  s.t  $x = f^{-1}(y), x \in D_f, y \in R_f$   
[ Inverse of a fn only exists if fn is bijective ]

Note: [ Just like fns, similar logic can be applied to linear transformation ]

- (i)  $T$  is non-singular iff  $T$  is one-one  $\checkmark$
- (ii)  $T$  is invertible ( $T^{-1}$  exists) iff  $T$  is non-singular
- (iii)  $T$  is invertible iff  $T$  is onto.

Non-singular  $T \Rightarrow N(T) = \{ \underline{0} \}$ .

$\therefore T(\underline{u}) = \underline{0} \Rightarrow u = 0$

$$T [ c_1 \underline{\alpha} + c_2 \underline{\beta} ] = c_1 T(\underline{\alpha}) + c_2 T(\underline{\beta})$$

$$\text{Kernel } \Rightarrow \mathcal{N}(T) = \{ \underline{0} \}$$

$$\therefore T(\underline{u}) = \underline{0} \Rightarrow \underline{u} = \underline{0}$$

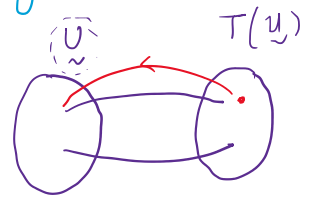
$$T[c_1 \underline{\alpha} + c_2 \underline{\beta}] = c_1 T(\underline{\alpha}) + c_2 T(\underline{\beta})$$

$$\text{Injectivity} \Rightarrow T(\underline{u}_1) = T(\underline{u}_2), \quad \underline{u}_1, \underline{u}_2 \in U$$

$$\Rightarrow T(\underline{u}_1) - T(\underline{u}_2) = \underline{0}$$

$$\Rightarrow T(\underline{u}_1 - \underline{u}_2) = \underline{0}$$

$$\Rightarrow \underline{u}_1 - \underline{u}_2 = \underline{0} \Rightarrow \underline{u}_1 = \underline{u}_2$$



$$\text{Non-singular} \Leftrightarrow \text{Injectivity} \Leftrightarrow T^{-1} \text{ exists}$$

$$8. T(x, y, z) = (x \cos \theta - y \sin \theta, x \sin \theta + y \cos \theta, z)$$

check for singularity of  $T$ .

$$\mathcal{N}(T) = \{ (x, y, z) \mid T(x, y, z) = (0, 0, 0) \}$$

$$T(x, y, z) = (0, 0, 0)$$

$$(x \cos \theta - y \sin \theta, x \sin \theta + y \cos \theta, z) = (0, 0, 0)$$

$$\Rightarrow \left. \begin{array}{l} x \cos \theta - y \sin \theta = 0 \\ x \sin \theta + y \cos \theta = 0 \\ z = 0 \end{array} \right\} \Rightarrow x = 0, y = 0, z = 0$$

$$\mathcal{N}(T) = \{ \underline{0} \} \Rightarrow \text{Non-singularity}$$

8. Consider  $T(x, y) = (\alpha x + \beta y, \gamma x + \delta y)$ . Determine the condition under which  $T^{-1}$  exist.

$$T(x, y) = \underline{0}$$

$$(\alpha x + \beta y, \gamma x + \delta y) = (0, 0)$$

$$\begin{vmatrix} \alpha & \beta \\ \gamma & \delta \end{vmatrix} \neq 0$$

$$\left\{ \begin{array}{l} \alpha x + \beta y = 0 \\ \gamma x + \delta y = 0 \end{array} \right\} \Rightarrow \text{Solving}$$

$$\alpha \delta - \beta \gamma \neq 0 \Rightarrow x = y = 0$$

$$\alpha \delta \neq \beta \gamma \Rightarrow T \text{ is non-singular}$$

$$\Rightarrow T^{-1} \text{ exists}$$

↳ Homogeneous system

Q.  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$  s.t.  $T(x, y, z) = (x, y)$ . Check if its one-one.

Q.  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$  s.t.  $T(x, y, z) = (x-y, y-z)$ . Check if its one-one.

$$N(T) = \underline{0} \Rightarrow (x-y, y-z) = (0, 0)$$

$$\left. \begin{array}{l} x-y = 0 \\ y-z = 0 \end{array} \right\} \Rightarrow x = y = z = k \text{ (say).}$$

$$N(T) = \{ (k, k, k) \} = \{ k(1, 1, 1) \} \Rightarrow \text{singular.}$$

Q.  $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$  s.t.  $T(x, y, z) = (x-y, y)$   $\Rightarrow$  Not one-one.